Lecture 10 GMM

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Method of Moments (MM): Review

- <u>Idea</u>: Population moment conditions provide information which can be used to estimate population parameters.
- Suppose we want to estimate the population mean μ variance σ^2 of a random variable v_t . These parameters satisfy the population moment conditions:

$$E[v_t] - \mu = 0$$

 $E[v_t^2] - (\sigma^2 + \mu^2) = 0$

• We move from population conditions to their analogous sample moment conditions:

$$\frac{1}{T} \sum_{t=1}^{T} v_t - \mu^* = 0 \qquad \Rightarrow \mu^* = \frac{1}{T} \sum_{t=1}^{T} v_t
\frac{1}{T} \sum_{i=1}^{T} v_t^2 - (\sigma^{*2} + \mu^{*2}) = 0 \Rightarrow \sigma^{*2} = \frac{1}{T} \sum_{t=1}^{T} (v_t - \mu^*)^2$$

Method of Moments: Review

• Example: A supply and demand system for wheat:

$$q_t^D = \alpha p_t + u_t^D$$

 $q_t^S = \beta_1 n_t + \beta_2 p_t + u_t^S$
 $q_t^D = q_t^S = q_t$

where q_t^D , q_t^S are quantity demanded and supplied; p_t is price, n_t is a weather variable. We want to estimate α .

Problem: Endogeneity, OLS –i.e., regress q_t^D against p_t – will not work

Solution: IV. Find z_t^D such that $cov(z_t^D, u_t^D) = 0$. Then,

$$cov(\mathbf{z}_t^D, \mathbf{q}_t) - \alpha cov(\mathbf{z}_t^D, \mathbf{p}_t) = 0$$

Method of Moments: Review

Example (continuation): $cov(z_t^D, q_t) - \alpha cov(z_t^D, p_t) = 0$

Then, if $E[u_t^D] = 0$, we have:

$$E[z_t^D q_t] - \alpha E[z_t^D p_{tt}] = 0$$
 (population condition)

The MM leads to

$$\hat{\alpha} = \frac{1}{T} \sum_{i=1}^{T} z_t^D q_t / \frac{1}{T} \sum_{i=1}^{T} z_t^D p_t$$
 (IV estimator)

Method of Moments: Review

- Population moment condition: A vector of observed variables, v_t , and vector of k parameters θ , satisfy a kx1 element vector of conditions $E[f(v_t, \theta)] = 0$ for all t.
- The MM estimator $\boldsymbol{\theta}_T^*$ solves the analogous sample moment conditions

$$g_t(\boldsymbol{\theta}^*) = \frac{1}{T} \sum_{t=1}^{T} f(\boldsymbol{v}_t, \boldsymbol{\theta}_T^*) = \mathbf{0}$$
 (1)

where *T* is the sample size.

• Under the usual regularity conditions, $\theta_T^* \xrightarrow{p} \theta_0$, where θ_0 is the solution of $E[f(v_t, \theta)] = 0$.

Note: We have k unknowns and k equations \Rightarrow unique solution.

Generalized Method of Moments (GMM)

- Now, suppose f is a $q \times 1$ vector and q > k. That is, we have k unknowns and q equations \Rightarrow not a unique solution.
- GMM picks a value for θ such that it comes closest to satisfy

$$g_T(\boldsymbol{\theta}^*) = \frac{1}{T} \sum_{t=1}^T f(\boldsymbol{v}_t, \boldsymbol{\theta}_T^*) = \mathbf{0}$$
 (qx1 equations)

• We define "closeness" by

$$Q_T(\boldsymbol{\theta}) = \left[\frac{1}{T} \sum_{t=1}^T f(\boldsymbol{v}_t, \boldsymbol{\theta}_T^*)\right]' \boldsymbol{W}_T \left[\frac{1}{T} \sum_{t=1}^T f(\boldsymbol{v}_t, \boldsymbol{\theta}_T^*)\right]$$
$$= \boldsymbol{g}_T(\boldsymbol{\theta}^*)' \boldsymbol{W}_T \boldsymbol{g}_T(\boldsymbol{\theta}^*)$$

where W_T is $(q \times q)$ psd matrix & $plim(W_T) = W$ pd

GMM: Example 1

- Power utility based asset pricing model –Hansen & Singleton (1982)
 - Theory condition:

 $E_{t}[\{\beta(c_{t+1}/c_{t})^{\gamma}\left(1+R_{i,t+1}\right)-1\}]=0 \qquad \text{with unknown}$ parameters β, γ

- The q population unconditional moment conditions are

- The q sample moment conditions are

$$\frac{1}{T} \sum_{t=1}^{T} Z_{j,t} \left\{ \beta_T^* \left(c_{t+1} / c_t \right)^{\gamma_T^*} \left(1 + R_{i,t+1} \right) - 1 \right\} = 0.$$

GMM: Example 2

- The CAPM
 - Theory condition:

$$E[r_{i,t+1} - \lambda_0(1-\beta_i) - \beta_i r_{m,t+1}] = 0$$

- The q population moment conditions (Market efficiency):

$$E[(r_{i,t+1} - \lambda_0(1 - \beta_i) - \beta_i r_{m,t+1}) Z_{j,t}] = 0 \quad j = 1,..., q$$

- The *q* sample moment conditions:

$$\frac{1}{T} \sum_{t=1}^{T} \{ r_{i,t+1} - \lambda_{0,T}^* (1 - \beta_i) - \beta_{i,T}^* r_{m,t+1}) Z_{j,t} \} = 0.$$

GMM: Example 3 - MLE

- Suppose the conditional pdf of the continuous stationary random vector v_t , given $V_{t-1} = \{v_{t-1}, v_{t-2}, ...\}$ is $p(v_t; \theta_0, V_{t-1})$
- The MLE of θ_0 based on the conditional log likelihood function is the value of which maximizes $L_T(\theta) = \sum_{i=1}^{n} \ln\{p(v_t; \theta, V_{t-1})\}$.

$$\Rightarrow$$
 solving $\frac{\delta L_T(\theta)}{\delta \theta} = 0$

• That is, the MLE is just the GMM estimator based on the population moment condition

$$E\left[\frac{\delta \ln\{p(v_t; \boldsymbol{\theta}, V_{t-1})\}}{\delta \boldsymbol{\theta}}\right] = 0$$

GMM: Summary

• The GMM estimator $\boldsymbol{\theta}_T^*$ = $\operatorname{argmin}_{\theta \in \Theta} Q_T(\boldsymbol{\theta})$ generates the f.o.c.

$$\left[\frac{1}{T}\sum_{t=1}^{T}\frac{\delta f(\boldsymbol{v}_{t},\boldsymbol{\theta}_{T}^{*})}{\delta\boldsymbol{\theta}'}\right]'\boldsymbol{W}_{T}\left[\frac{1}{T}\sum_{t=1}^{T}f(\boldsymbol{v}_{t},\boldsymbol{\theta}_{T}^{*})\right]=\boldsymbol{0} \tag{**}$$

where $\frac{\delta f(v_t, \theta_T^*)}{\delta \theta'}$ is a $q \times k$ matrix with i, j element $\frac{\delta f_i(v_t, \theta_T^*)}{\delta \theta_j}$

• There is typically no closed form solution for θ_T^* so it must be obtained through numerical optimization methods.

<u>Note</u>: From (**), the GMM estimator is the MM estimator based on population moments:

$$\{ E[\frac{\delta f(\boldsymbol{v}_t, \boldsymbol{\theta}_0)}{\delta \boldsymbol{\theta}}] \}' \boldsymbol{W} \{ E[f(\boldsymbol{v}_t, \boldsymbol{\theta}_0)] \} = \boldsymbol{0}$$
 (kx1 conditions)

Example: IV estimation of linear model

• Linear IV framework:

$$y = X\theta_0 + \varepsilon$$
, with $E[X'\varepsilon] \neq 0$.

- Let Z be a $T \times q$ vector of IV –i.e., $E[Z'\varepsilon] = 0$ and $E[Z'X] \neq 0$.
- We want to estimate $\boldsymbol{\theta}_0$ using GMM. Then, the GMM estimator $\boldsymbol{\theta}_T^* = \operatorname{argmin}_{\theta \in \Theta} \{Q_T(\boldsymbol{\theta}) = [\boldsymbol{\varepsilon}(\boldsymbol{\theta})\boldsymbol{Z}'/T] \boldsymbol{W}_T [\boldsymbol{Z}'\boldsymbol{\varepsilon}(\boldsymbol{\theta})/T] \}$ (kx1) f.o.c.:

$$(\mathbf{X}'\mathbf{Z}/T) \mathbf{W}_T (\mathbf{Z}' \boldsymbol{\varepsilon}(\boldsymbol{\theta}_T^*)/T) = 0$$

 $(\mathbf{X}'\mathbf{Z}/T) \mathbf{W}_T (\mathbf{Z}' (\mathbf{y} - \mathbf{X}\boldsymbol{\theta}_T^*)/T) = 0$

or

$$\Rightarrow$$
 $(X'Z/T) W_T (Z'y/T) = (X'Z/T) W_T (Z'X/T) \theta_T^*$

Example: IV estimation of linear model

• From f.o.c.: $(X'Z/T) W_T (Z'y/T) = (X'Z/T) W_T (Z'X/T) \theta_T^*$

CASE 1: q = k -i.e., just-identified- and $(\mathbf{Z}'\mathbf{X}/T)$ is nonsingular then $\boldsymbol{\theta}_T^* = (\mathbf{Z}'\mathbf{X}/T)^{-1} (\mathbf{Z}'\mathbf{y}/T)$

independently of the weighting matrix W_T .

CASE 2: q > k -i.e., over-identified.

$$\boldsymbol{\theta}_T^* = \{ \left(\frac{X'Z}{T} \right) \boldsymbol{W}_T \left(\frac{Z'X}{T} \right) \}^{-1} \left(\frac{X'Z}{T} \right) \boldsymbol{W}_T \left(\frac{Z'y}{T} \right)$$

Note: GMM = MM based on (kx1) population moment conditions

$$\mathrm{E}[\mathbf{X}'\mathbf{Z}] \mathbf{W} \mathrm{E}[\mathbf{Z}'\boldsymbol{\varepsilon}(\boldsymbol{\theta}_0)] = \mathbf{0}$$

- (1) When q = k GMM = MM based on $E[\mathbf{Z}'\boldsymbol{\varepsilon}(\boldsymbol{\theta}_0)] = \mathbf{0}$.
- (2) When q > k GMM sets k linear combinations of $E[\mathbf{Z}' \boldsymbol{\varepsilon}(\boldsymbol{\theta}_0)] = \mathbf{0}$. But, in order to estimate $\boldsymbol{\theta}_0$, we only need k conditions!

Identifying and overidentifying restrictions

• Recall (**). The GMM estimator is the MM estimator based on (*k*x1) population moments

$$\{E\left[\frac{\delta f(\boldsymbol{v}_{t},\boldsymbol{\theta}_{0})}{\delta \boldsymbol{\theta}}\right]\}' \boldsymbol{W} \{E\left[f(\boldsymbol{v}_{t},\boldsymbol{\theta}_{0})\right]\} = 0 \qquad (***)$$

- Let $\mathbf{F}(\boldsymbol{\theta}_0) = \mathbf{W}^{1/2} E[\frac{\delta f(\boldsymbol{v}_t, \boldsymbol{\theta}_0)}{\delta \boldsymbol{\theta}}]$ (a $q \times k$ matrix), with rank $(\mathbf{F}(\boldsymbol{\theta}_0)) = k$. (The *rank condition* is necessary for identification of $\boldsymbol{\theta}_0$).
- Rewrite (***) as

$$F(\theta_0) W^{1/2} E[f(v_t, \theta_0)] = 0 \text{ or } (k \text{ equations})$$

$$\mathbf{F}(\boldsymbol{\theta}_0)[\mathbf{F}(\boldsymbol{\theta}_0)'\mathbf{F}(\boldsymbol{\theta}_0)]^{-1}\mathbf{F}(\boldsymbol{\theta}_0)' \boldsymbol{W}^{1/2}\mathbf{E}[f(\boldsymbol{v}_t,\boldsymbol{\theta}_0)] = \boldsymbol{P}_F' \boldsymbol{W}^{1/2}\mathbf{E}[f(\boldsymbol{v}_t,\boldsymbol{\theta}_0)] = \mathbf{0}$$

• The LS projection of $W^{\frac{1}{2}}E[f(v_t, \theta_0)]$ on to the column space of $F(\theta_0)$ is 0.

Identifying and overidentifying restrictions

• That is, the GMM estimator is based on rank $\{P_F\}$ = k restrictions on the $(q \times 1)$ (transformed) population moment condition

$$\mathbf{W}^{1/2}E[f(\mathbf{v}_t,\boldsymbol{\theta}_0)].$$

- These are the *identifying restrictions*; GMM picks $\boldsymbol{\theta}_T^*$ to satisfy them.
- The restrictions that are left over are

$$\{\boldsymbol{I}_q - \boldsymbol{P}_F\}' \boldsymbol{W}^{1/2} E[f(\boldsymbol{v}_t, \boldsymbol{\theta}_0)] = 0$$

- That is, the projection of $W^{\frac{1}{2}}E[f(v_t, \theta_0)]$ on to the orthogonal complement of $F(\theta_0)$ is zero, generating q-k restrictions on the transformed population moment condition.
- These over-identifying restrictions are ignored by the GMM estimator!

Identifying and overidentifying restrictions

- The **over-identifying restrictions** are ignored by the GMM estimator, so they need not be satisfied in the sample.
- From (**), $\boldsymbol{W}_{T}^{1/2}\left[\frac{1}{T}\sum_{t=1}^{T}f(\boldsymbol{v}_{t},\boldsymbol{\theta}_{T}^{*})\right] = \{\boldsymbol{I}_{q}-\boldsymbol{P}_{F}\}^{\prime}\boldsymbol{W}_{T}^{1/2}\left[\frac{1}{T}\sum_{t=1}^{T}f(\boldsymbol{v}_{t},\boldsymbol{\theta}_{T}^{*})\right]$

Thus, $Q_T(\boldsymbol{\theta}_T^*)$ is like a sum of squared residuals, and can be interpreted as a measure of how far the sample is from satisfying the over-identifying restrictions.

Asymptotic properties of GMM IVE

• Under the usual regularity conditions, it can be shown that:

$$(1) \; \boldsymbol{\theta}_T^* \stackrel{p}{\longrightarrow} \boldsymbol{\theta}_0$$

(2)
$$(\theta_{T,i}^* - \theta_{0,i})/[\sqrt{V_{T,ii}^*}/T] \stackrel{d}{\longrightarrow} N(0, 1)$$

where
$$V_T^* = (X'ZW_TZ'X)^{-1}X'ZW_T S_T^* W_TZ'X (X'ZW_TZ'X)^{-1}$$

 $S_T^* = \lim_{T\to\infty} \text{Var}[Z'\varepsilon/T]$

• Assuming $\boldsymbol{\varepsilon}$ is serially uncorrelated

$$Var[\mathbf{Z}'\boldsymbol{\varepsilon}/T] = E[\{\frac{1}{\sqrt{T}}\sum_{t=1}^{T} z_{t} \varepsilon_{t}\} \{\frac{1}{\sqrt{T}}\sum_{t=1}^{T} z_{t} \varepsilon_{t}\}']$$
$$= \frac{1}{T}\sum_{t=1}^{T} E[\varepsilon_{t}^{2} z_{t} z_{t}']$$

• Thus,

$$\mathbf{S}_T^* = \frac{1}{T} \left[\sum_{t=1}^T \boldsymbol{\varepsilon} (\boldsymbol{\theta}_T^*)_t^2 \mathbf{z}_t \mathbf{z}_t' \right]$$

GMM: Two-step estimator

• The asymptotic variance depends on the weighting matrix W_T .

The optimal choice is $W_T = S_T^{*-1}$ to give $V_T^* = (X'Z S_T^{*-1}Z'X)^{-1}$

- But we need $\boldsymbol{\theta}_T^*$ to construct \boldsymbol{S}_T^* . This suggests a two-step (iterative) GMM procedure:
 - (1) Start with sub-optimal $W_T(0)$, say I
- (2) Using $W_T(0)$ estimate $\boldsymbol{\theta}_T^*(1) \& \boldsymbol{S}_T^*(1)$
- (3) Estimate with $W_T(1) = S_T^*(1)^{-1}$
- (4) Using $W_T(j)$ repeat steps (2)-(3) to get $\boldsymbol{\theta}_T^*(j+1)$ & $\boldsymbol{S}_T^*(j+1)$ until convergence.

GMM: Two-step estimator

• Note that if **\varepsilon** is homoskedastic:

$$\operatorname{Var}[\boldsymbol{\varepsilon} \mid \boldsymbol{X}] = \sigma^2 \; \mathbf{I}_{\mathrm{T}} \qquad \Rightarrow \boldsymbol{S}_T^* = s^{*2} \boldsymbol{Z} \boldsymbol{Z}'$$

where s^{*2} is a consistent estimator of σ^2 .

• Choosing this S_T^* to construct the weighting matrix $W_T = S_T^{*-1}$. Then,

$$\boldsymbol{\theta}_{T}^{*} = (\boldsymbol{X}'\boldsymbol{Z} (s^{*2}\boldsymbol{Z}\boldsymbol{Z}')^{-1}\boldsymbol{Z}'\boldsymbol{X})^{-1} \boldsymbol{X}'\boldsymbol{Z} (s^{*2}\boldsymbol{Z}\boldsymbol{Z}')^{-1}\boldsymbol{Z}'\boldsymbol{y}$$
$$= \{\widehat{\boldsymbol{X}}'\widehat{\boldsymbol{X}}\}^{-1}\widehat{\boldsymbol{X}}'\boldsymbol{y}$$

where $\hat{X} = P_z Z$ is the predicted value of X from a regression of X on Z. This is the 2SLS estimator.

Model specification test

- Identifying restrictions are satisfied in the sample regardless of whether the model is correct.
- Over-identifying restrictions are not imposed in the sample. We can use them to test the model.

Recall the qx1 population moment conditions $E[\mathbf{Z}'\boldsymbol{\varepsilon}(\boldsymbol{\theta}_0)] = \mathbf{0}$. We can construct a Wald-type test to check if these q conditions are met in sample. The **overidentifying restrictions test**:

$$J_T = T \ Q_T(\boldsymbol{\theta}_T^*) = T^{-1/2} \ \epsilon(\boldsymbol{\theta}_T^*)' \boldsymbol{Z} \ \boldsymbol{S}_T^{*-1} \ T^{-1/2} \ \boldsymbol{Z}' \boldsymbol{\varepsilon}(\boldsymbol{\theta}_T^*)$$

Under
$$H_0$$
: $E[\mathbf{Z}'\boldsymbol{\varepsilon}(\boldsymbol{\theta}_0)] = 0$, $J_T \xrightarrow{d} \chi_{q-k}^2$

Testing C-CAPM: GMM

• GMM can naturally be applied in the C-CAPM. The Euler's equation, gives us a starting point for a moment condition:

$$0 = E_{t}[m(\boldsymbol{x}_{t+1}, \boldsymbol{\theta}_{0}) (1 + R_{i,t+1}) - 1]$$

• Let Z_t be a set of $l(l \ge k)$ instruments, available at time t. Then, for each asset i:

$$\mathrm{E}_{\mathbf{t}}[\mathbf{Z}_{j,t}\{\beta(c_{t+1}/c_{t})^{\gamma}\left(1+\,R_{i,t+1}\right)-1\}]=0\ \ i=1,\ldots,N; j=1,\ldots,l.$$

Note: Now we have a lot of moments: lxN!

• GMM works with sample analogues of the population moments:

$$g(\boldsymbol{v}_t, \boldsymbol{\theta}_T^*) = \frac{1}{T} \sum_{t=1}^T \boldsymbol{Z}_{j,t} \left\{ \beta_T^* \left(c_{t+1}/c_t \right)^{\gamma_T^*} \left(1 + R_{i,t+1} \right) - 1 \right\} = 0.$$

Testing C-CAPM: GMM - Remarks

- Q: How do we choose \mathbf{Z}_t the l instruments? Not a trivial question. In general, predetermined regressors used to be viewed with a positive light. Today, they are viewed as "acceptable," in some settings. In many settings, especially, with macro series/indexes they are not.
- <u>Note</u>: Recall that weak instruments are a problem. In theory, we only need small correlation between Z_t and the model's variables. However, the bigger the correlation, the better:
 - \Rightarrow 50 weak instruments are no substitute for a good IV!
- Advantages of GMM approach:
 - All we need is a moment condition.
 - No need to log-linearize anything.
 - Non-linearities are not a problem.
 - Robust to heteroscedasticiy and distributional assumptions.

Testing C-CAPM: GMM - Remarks

- Practical Considerations:
- We need at least as many moment conditions as parameters (just-identified case).
- If there are more moments –the usual case-, we have "over-identifying restrictions." Use them to test the model (*J*-test):

$$J = T \ Q_T(\boldsymbol{\theta}_T^*) = T^{-1/2} \ g(\boldsymbol{v}_t, \boldsymbol{\theta}_T^*)' \ \boldsymbol{S}_T^{*-1} g(\boldsymbol{v}_t, \boldsymbol{\theta}_T^*) \sim \chi_{\text{Lx}N-k}^2$$
 where $\boldsymbol{S}_T^* = \text{Var}[g(\boldsymbol{v}_t, \boldsymbol{\theta}_T^*)]$

- Too many moments are not desirable in practice.
- The instruments (conditioning information) matter.

Testing C-CAPM: GMM - Remarks

- Practical Considerations:
- Estimating **S** is tricky. In general, the moments will be serially dependent. Newey-West (1987) does not work well when the dimensions of the system is large. Small changes to **S** produces big swings in estimated **θ**. (Sometimes is better to work with **W**=**I**!)
- Some questions regarding the small sample properties of GMM.
- The over-identifying restrictions are subject to a "which moments to choose?" critique.
- The J test also depends crucially on S; difficult to estimate accurately
- Not surprisingly, the J test rejects a lot of models. We should be aware of its problems.

Testing C-CAPM: GMM - Example

• Taken from Hansen and Singleton (1982).

For each asset i, H&S have:

$$E_{t}[\mathbf{Z}_{t}\{\beta(c_{t+1}/c_{t})^{\gamma}(1+R_{i,t+1})-1\}]=0$$
 $i=1,...,N$.

 $R_{i,t}$ = NYSE stock returns (VW and EW).

 c_t = Consumption (Non-durables (ND) & ND plus services (NDS).)

 \mathbf{Z}_t = lagged $R_{i,t+1}$ and c_{t+1}/c_t . (H&S use 1, 2, 4 and 6 lags.)

<u>Findings</u>: $\beta \approx 1$ (around .99) and γ small (between .32 to .03.) J-tests reject C-CAPM.

- General problem with IVE of the C-CAPM: weak instruments. It's difficult to find IVs highly correlated with consumption growth.
- According to Hall's (1978) consumption follows a random walk: lagged $R_{i,t+1}$ and c_{t+1}/c_t should have low correlation with c_{t+1}/c_t !

GMM estimation – General Case

- Go back to GMM estimation but let f be a vector of continuous nonlinear functions of the data and unknown parameters.
- In our case, we have N assets and the moment condition is: $\mathrm{E}[\{m(x_t,\,\theta_0)\,\big(1+\,R_{i,t}\big)-1\}\,\,z_{j,t-1}]=\mathrm{E}[\epsilon_t\,\,z_{j,t-1}]=0,$ using (lagged) instruments $z_{j,t-1}$ for each asset $i=1,\ldots,N$ and each instrument $j=1,\ldots,q$.
- Collect these as $f(v_t, \theta) = z_{t-1}' \otimes \varepsilon_t(x_t, \theta)$, where z_t is a $1 \times q$ vector of instruments and ε_t is a $N \times 1$ vector. f is a column vector with q N elements it contains the cross-product of each instrument with each element of ε .
- Population moment condition: $E[f(v_t, \theta_0)] = 0$

GMM estimation – General Case

• The population moment condition is

$$\mathrm{E}[\boldsymbol{f}(\boldsymbol{v}_t,\boldsymbol{\theta}_0)] = 0$$

- As before, let $\boldsymbol{g}_T(\boldsymbol{\theta}) = [\frac{1}{T} \sum_{t=1}^T f(\boldsymbol{v}_t, \boldsymbol{\theta})]$. The GMM estimator is $\boldsymbol{\theta}_T^* = \operatorname{argmin}_{\theta \in \Theta} Q_T(\boldsymbol{\theta})$
- The f.o.c.'s are

$$\boldsymbol{G}_{T}(\boldsymbol{\theta}_{T}^{*})' \boldsymbol{W}_{T} \boldsymbol{g}_{T}(\boldsymbol{\theta}_{T}^{*}) = 0$$

where $G_T(\theta_T^*)$: Matrix of partial derivatives with i, j element $\delta g_{T,i}/\delta \theta_j$

GMM Asymptotics: General Case

It can be shown that:

$$(1) \; \boldsymbol{\theta}_T^* \stackrel{p}{\longrightarrow} \boldsymbol{\theta}_0$$

$$(2) (\theta_{T,i}^* - \theta_{0,i}) / [\sqrt{\boldsymbol{V}_{T,ii}^*} / T] \stackrel{d}{\longrightarrow} N(0, 1)$$

where Asy $Var(\theta_{T,i}^*) = V = M S M'$ where

$$- \mathbf{M} = (\mathbf{G_0}' \mathbf{W} \mathbf{G_0})^{-1} \mathbf{G_0}' \mathbf{W}$$

-
$$G_0 = \mathbb{E}[\partial f(v_t, \boldsymbol{\theta}_0)/\partial \boldsymbol{\theta}']$$

-
$$\boldsymbol{S} = \lim_{T \to \infty} \operatorname{Var}[T^{-1/2} \boldsymbol{g}_T(\boldsymbol{\theta}_0)]$$

(3) A test of the model's over-identifying restrictions is given by

$$J_T = T \ Q_T(\boldsymbol{\theta}_T^*) \qquad \stackrel{d}{\longrightarrow} \chi_{qN-k}^2$$

Covariance matrix estimation for GMM

• In practice $V_T^* = M_T^* S_T^* M_T^{*'}$ is a consistent estimator of V, where

-
$$\boldsymbol{M}_{T}^{*} = [\boldsymbol{G}_{T}(\boldsymbol{\theta}_{T}^{*})' \boldsymbol{W}_{T} \boldsymbol{G}_{T}(\boldsymbol{\theta}_{T}^{*})]^{-1} \boldsymbol{G}_{T}(\boldsymbol{\theta}_{T}^{*})' \boldsymbol{W}_{T}$$

- \boldsymbol{S}_T^* is a consistent estimator of \boldsymbol{S}
- Estimator of S depends on time series properties of $f(v_t, \theta_0)$. In general, it is

$$\mathbf{S} = \mathbf{\Gamma}_0 + \Sigma (\mathbf{\Gamma}_i + \mathbf{\Gamma}_i')$$

where $\Gamma_i = \mathrm{E}\{f_t - \mathrm{E}(f_t)\}\{f_{t-i} - \mathrm{E}(f_{t-i})\}' = \mathrm{E}[f_t \ f_{t-i}']$ is the *i-th* autocovariance matrix of $f_t = f(\boldsymbol{v}_t, \boldsymbol{\theta}_0)$.

• We can consistently estimate **S** with

$$\boldsymbol{S}_{T}^{*} = \boldsymbol{\Gamma}_{0}^{*}(\boldsymbol{\theta}_{T}^{*}) + \boldsymbol{\Sigma} \left\{ \boldsymbol{\Gamma}_{i}^{*}(\boldsymbol{\theta}_{T}^{*}) + \boldsymbol{\Gamma}_{i}^{*}(\boldsymbol{\theta}_{T}^{*})' \right\}$$

where

$$\Gamma_i^*(\boldsymbol{\theta}_T^*) = \frac{1}{T} \sum_{t=1}^T f(\boldsymbol{v}_t, \boldsymbol{\theta}_T^*) * f(\boldsymbol{v}_{t-i}, \boldsymbol{\theta}_T^*)'$$

Covariance matrix estimation for GMM

• If theory implies that the autocovariances of $f(v_t, \theta_0) = 0$ for some lag i, then we can exclude these from S_T^* –e.g., $\varepsilon_t = \varepsilon(v_t, \theta_T^*)$ are serially uncorrelated implies

$$\boldsymbol{S}_{T}^{*} = \frac{1}{T} \sum_{t=1}^{T} \left\{ \boldsymbol{\varepsilon}(\boldsymbol{v}_{t}, \boldsymbol{\theta}_{T}^{*}) \; \boldsymbol{\varepsilon}(\boldsymbol{v}_{t}, \boldsymbol{\theta}_{T}^{*})' \; \otimes \; (\boldsymbol{z_{t}}' \boldsymbol{z}_{t}) \right\}$$

GMM Adjustments

- Iterated GMM is recommended in small samples
- More powerful tests by subtracting sample means of $f(v_t, \theta_T^*)$ in calculating $\Gamma_i^*(\theta_T^*)$
- Asymptotic standard errors may be understated in small samples: multiply asymptotic variances by "degrees of freedom adjustment" T/(T-k) or $\left\{\frac{(N+q)T}{(N+q)T-k}\right\}$.