

Continuous Random Variables

Joint Probability Density Function (pdf)

Definition: Joint Probability density function

Two random variable are said to have *joint probability density function* f(x, y) if

- 1. $f(x,y) \ge 0.$
 - 2. $\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x, y) \, dx \, dy = 1.$
 - 3. $P[(X,Y) \in A] = \int_A \int_A f(x,y) \, dx \, dy$

Marginal and Condition Density

Definition: Marginal Density

Let X and Y denote two RVs with joint pdf f(x, y), then the *marginal* density of X is

$$f_X(x) = \int_{-\infty}^{\infty} f(x, y) \, dy$$

and the marginal density of Y is $f_Y(y) = \int_{-\infty}^{\infty} f(x, y) dx$

Definition: Conditional Density

Let X and Y denote two RVs with joint pdf f(x, y) and marginal densities $f_X(x)$, $f_Y(y)$, then the *conditional density* of Y given X = x and the conditional density of X given Y = y are given by

$$f_{Y|X}\left(y\left|x\right.\right) = \frac{f\left(x,y\right)}{f_{X}\left(x\right)} \qquad \qquad f_{X|Y}\left(x\left|y\right.\right) = \frac{f\left(x,y\right)}{f_{Y}\left(y\right)}$$

Joint MGF

Definition: MGF of (X, Y)

Let X and Y be two RVs with joint pdf f(x, y), then the MGF of X & Y:

$$m_{XY}(t_1, t_2) = E[\exp(t_1 X + t_2 Y)] = \iint_{R^2} \exp(t_1 X + t_2 Y) f(x, y) dx dy$$

Theorem:

The MGF of a pair of independent RVs is the product of the MGF of the corresponding marginal distributions. That is,

Proof

$$m_{XY}(t_1, t_2) = m_X(t_1) m_Y(t_2)$$

of:
$$m_{XY}(t_1, t_2) = \iint \exp(t_1 X + t_2 Y) f(x, y) dx dy$$

$$= \iint \exp(t_1 X) \exp(t_2 Y) f(x) f(y) dx dy$$

$$= \int \exp(t_1 X) f(x) dx \int \exp(t_2 Y) f(y) dy = m_X(t_1) m_Y(t_2)$$

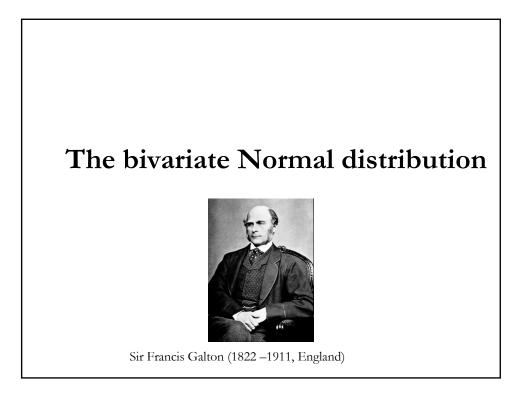
Marginal MGF

Definition: MGF of the marginal distribution of X (and Y) Let $m_{XY}(t_1, t_2)$ be the MGF of (X, Y), then the MGF of the marginal distributions of X and Y are, respectively, $m_{XY}(t_1, 0)$ and $m_{XY}(0, t_2)$

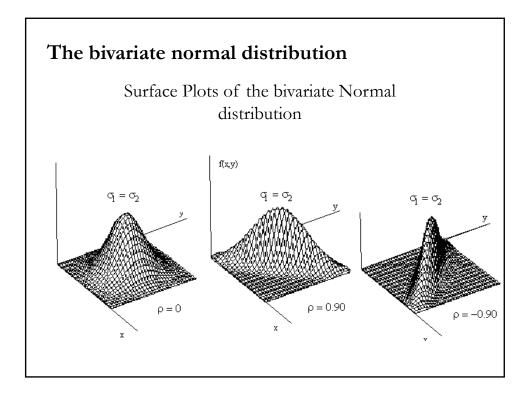
Proof:

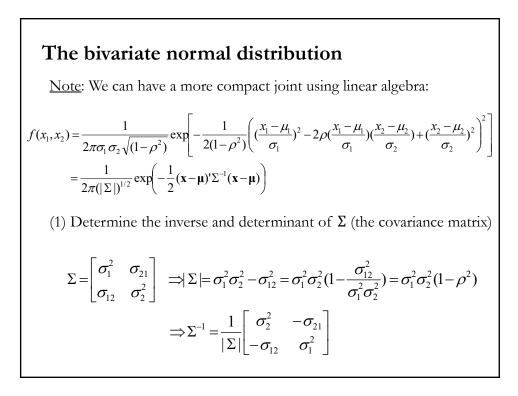
$$m_X(t) = \int_{-\infty}^{\infty} \exp(tX) f_X(x) dx = \int_{-\infty}^{\infty} \exp(tX) \left[\int_{-\infty}^{\infty} f_{XY}(x, y) dy \right] dx =$$
$$= \iint_{-\infty} \exp(tX) f_{XY}(x, y) dy dx = m_{XY}(t, 0)$$

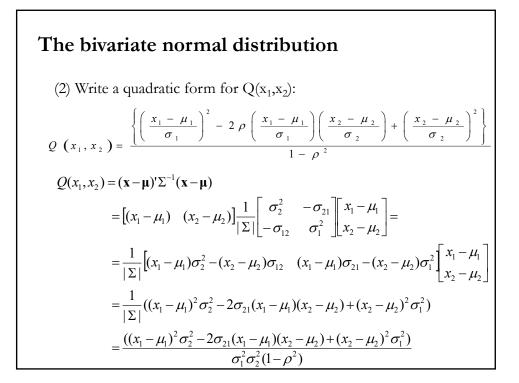
Similar derivation for Y.

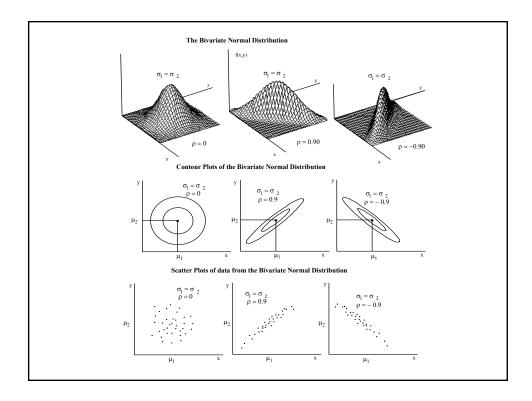


The bivariate normal distribution Let the joint distribution be given by: $f(x_1, x_2) = \frac{1}{(2\pi)\sigma_1\sigma_2} \sqrt{1-\rho^2} e^{-\frac{1}{2}\varrho(x_1, x_2)}$ where $\varrho(x_1, x_2) = \frac{\left\{ \left(\frac{x_1 - \mu_1}{\sigma_1}\right)^2 - 2\rho\left(\frac{x_1 - \mu_1}{\sigma_1}\right)\left(\frac{x_2 - \mu_2}{\sigma_2}\right) + \left(\frac{x_2 - \mu_2}{\sigma_2}\right)^2 \right\}}{1-\rho^2}$ This distribution is called the *bivariate Normal distribution*. The parameters are $\mu_1, \mu_2, \sigma_1, \sigma_2$ and ρ . The properties of this distribution were studied by Francis Galton and discovered its relation to the regression, term Galton coined.









The bivariate normal distribution: MGF

Let MGF of a bivariate normal is given by:

$$m_{XY}(t_1, t_2) = \exp[t_1 \mu_X + t_2 \mu_Y - \frac{1}{2}(t_1^2 \sigma_X^2 + t_2^2 \sigma_Y^2 + 2\rho_{XY} t_1 t_2 \sigma_X \sigma_Y)]$$

<u>Note</u>: When $\rho_{XY} = 0$ –i.e., X and Y are independent. The MGF is:

$$m_{XY}(t_1, t_2) = \exp[t_1 \mu_X + t_2 \mu_Y - \frac{1}{2}(t_1^2 \sigma_X^2 + t_2^2 \sigma_Y^2)]$$

Marginal distributions for the Bivariate Normal

Recall the definition of marginal distributions for continuous RV:

$$f_1(x_1) = \int_{-\infty}^{\infty} f(x_1, x_2) dx_2$$
 and $f_2(x_2) = \int_{-\infty}^{\infty} f(x_1, x_2) dx_1$

In the case of the bivariate normal distribution the marginal distribution of x_i is Normal with mean μ_i and standard deviation σ_i .

Proof:

The marginal distributions of x_2 is

$$f_{2}(x_{2}) = \int_{-\infty}^{\infty} f(x_{1}, x_{2}) dx_{1} = \frac{1}{(2\pi)\sigma_{1}\sigma_{2}\sqrt{1-\rho^{2}}} \int_{-\infty}^{\infty} e^{-\frac{1}{2}Q(x_{1}, x_{2})} dx_{1}$$

where

$$Q(x_1, x_2) = \frac{\left\{ \left(\frac{x_1 - \mu_1}{\sigma_1}\right)^2 - 2\rho\left(\frac{x_1 - \mu_1}{\sigma_1}\right)\left(\frac{x_2 - \mu_2}{\sigma_2}\right) + \left(\frac{x_2 - \mu_2}{\sigma_2}\right)^2 \right\}}{1 - \rho^2}$$

Marginal distributions for the Bivariate Normal
Now:

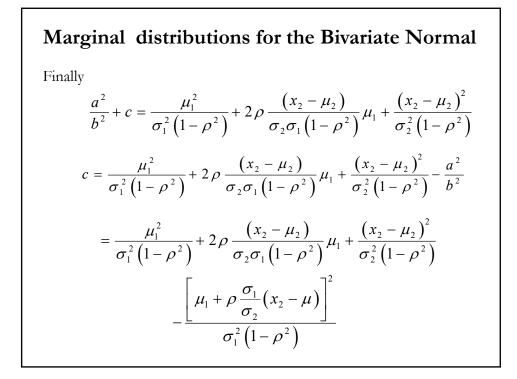
$$Q(x_1, x_2) = \frac{\left\{ \left(\frac{x_1 - \mu_1}{\sigma_1} \right)^2 - 2\rho \left(\frac{x_1 - \mu_1}{\sigma_1} \right) \left(\frac{x_2 - \mu_2}{\sigma_2} \right) + \left(\frac{x_2 - \mu_2}{\sigma_2} \right)^2 \right\}}{1 - \rho^2}$$

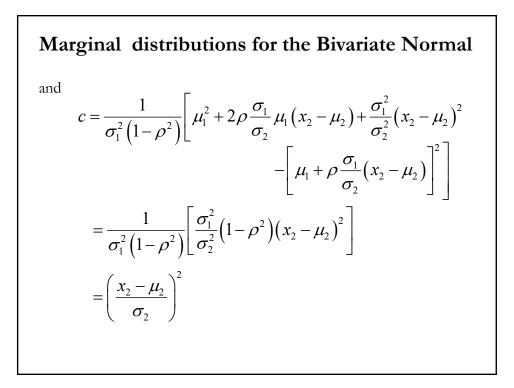
$$= \left(\frac{x_1 - a}{b} \right)^2 + c = \frac{x_1^2}{b^2} - 2\frac{a}{b^2}x_1 + \frac{a^2}{b^2} + c$$

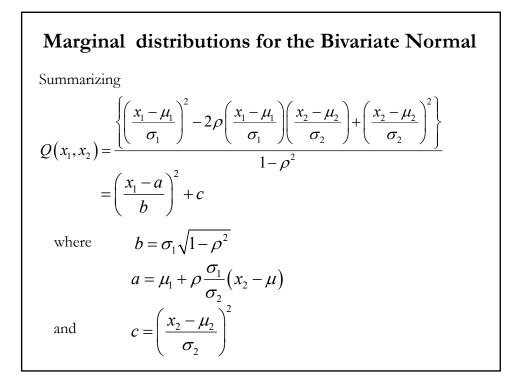
$$= \frac{x_1^2}{\sigma_1^2 \left(1 - \rho^2 \right)} - 2 \left[\frac{\mu_1}{\sigma_1^2 \left(1 - \rho^2 \right)} + \rho \frac{x_2 - \mu_2}{\sigma_2 \sigma_1 \left(1 - \rho^2 \right)} \right] x_1$$

$$+ \frac{\mu_1^2}{\sigma_1^2 \left(1 - \rho^2 \right)} + 2\rho \frac{(x_2 - \mu_2)}{\sigma_2 \sigma_1 \left(1 - \rho^2 \right)} \mu_1 + \frac{(x_2 - \mu_2)^2}{\sigma_2^2 \left(1 - \rho^2 \right)}$$

Marginal distributions for the Bivariate Normal
Hence
$$b^2 = \sigma_1^2 (1 - \rho^2)$$
 or $b = \sigma_1 \sqrt{1 - \rho^2}$
Also $\frac{a}{b^2} = \frac{\mu_1}{\sigma_1^2 (1 - \rho^2)} + \rho \frac{x_2 - \mu_2}{\sigma_2 \sigma_1 (1 - \rho^2)}$
 $= \frac{1}{\sigma_1^2 (1 - \rho^2)} \left[\mu_1 + \rho \frac{\sigma_1}{\sigma_2} (x_2 - \mu) \right]$
and
 $a = \mu_1 + \rho \frac{\sigma_1}{\sigma_2} (x_2 - \mu)$







Marginal distributions for the Bivariate Normal Thus $f_{2}(x_{2}) = \int_{-\infty}^{\infty} f(x_{1}, x_{2}) dx_{1}$ $= \frac{1}{(2\pi)\sigma_{1}\sigma_{2}\sqrt{1-\rho^{2}}} \int_{-\infty}^{\infty} e^{-\frac{1}{2}Q(x_{1}, x_{2})} dx_{1}$ $= \frac{1}{(2\pi)\sigma_{1}\sigma_{2}\sqrt{1-\rho^{2}}} \int_{-\infty}^{\infty} e^{-\frac{1}{2}\left[\left(\frac{x_{1}-a}{b}\right)^{2}+c\right]} dx_{1}$ $= \frac{\sqrt{2\pi}be^{-c/2}}{(2\pi)\sigma_{1}\sigma_{2}\sqrt{1-\rho^{2}}} \int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi}b} e^{-\frac{1}{2}\left(\frac{x_{1}-a}{b}\right)^{2}} dx_{1}$ $= \frac{1}{\sqrt{2\pi}\sigma_{2}} e^{-\frac{1}{2}\left(\frac{x_{2}-\mu_{2}}{\sigma_{2}}\right)^{2}}$

Marginal distributions for the Bivariate Normal

• Thus the marginal distribution of x_2 is Normal with mean μ_2 and standard deviation σ_2 .

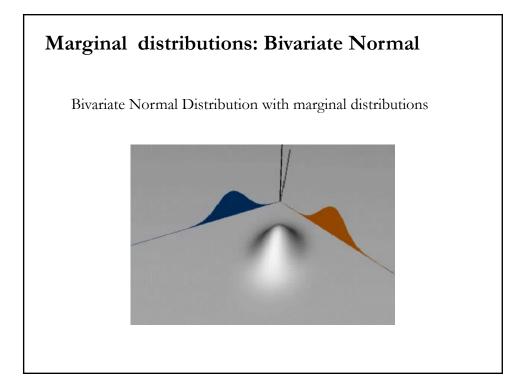
• Similarly, the marginal distribution of x_1 is Normal with mean μ_1 and standard deviation σ_1 .

Note: This derivation is much easier using MGFs.

Use the MGF of a bivariate normal. To get the MGF of the marginal of X, set $t_2=0$.

$$m_{XY}(t_1, t_2) = \exp[t_1\mu_X + t_2\mu_Y - \frac{1}{2}(t_1^2\sigma_X^2 + t_2^2\sigma_Y^2 + 2\rho_{XY}t_1t_2\sigma_X\sigma_Y)]$$

$$m_{XY}(t_1, 0) = \exp[t_1\mu_X - \frac{1}{2}(t_1^2\sigma_X^2)] = m_X(t_1)$$



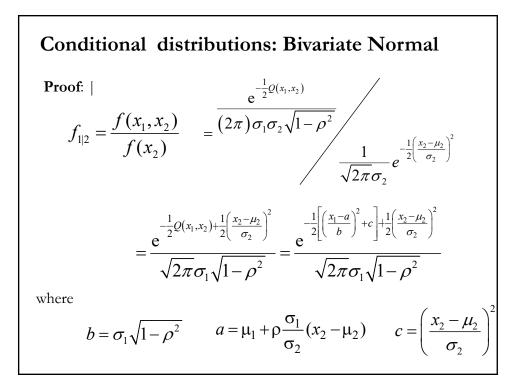
Conditional distributions for the Bivariate Normal

Recall the definition of conditional distributions for continuous RVs:

$$f_{1|2}(x_1|x_2) = \frac{f(x_1, x_2)}{f_2(x_2)} \quad \text{and} \quad f_{2|1}(x_2|x_1) = \frac{f(x_1, x_2)}{f_1(x_1)}$$

In the case of the bivariate normal distribution the conditional distribution of x_i given x_j is Normal with mean and standard deviation:

$$\mu_{i|j} = \mu_i + \rho \frac{\sigma_i}{\sigma_j} (x_j - \mu_j)$$
 and $\sigma_{i|j} = \sigma_i \sqrt{1 - \rho^2}$

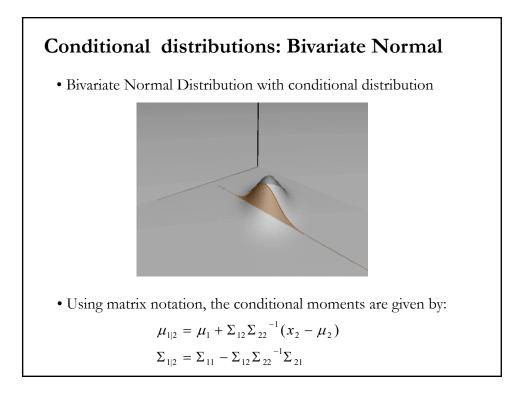


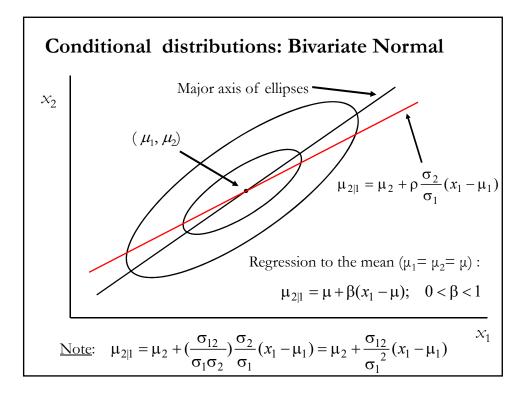
Conditional distributions: Bivariate Normal

Hence
$$f_{1|2}(x_1|x_2) = \frac{1}{\sqrt{2\pi b}} e^{-\frac{1}{2}(\frac{x_1-a}{b})^2}$$

Then, the conditional distribution of x_2 given x_1 is Normal with mean and standard deviation:

$$a = \mu_{1|2} = \mu_1 + \rho \frac{\sigma_1}{\sigma_2} (x_2 - \mu_2)$$
 and $b = \sigma_{1|2} = \sigma_1 \sqrt{1 - \rho^2}$





Conditional distributions: KF Application

• The Kalman filter (KF) uses the observed data to learn about the unobservable state variables, which describe the state of the model.

• KF models dynamically what we measure, z_t , and the state, y_t . In the simple, linear model we have:

$y_t = \mathbf{A} y_{t-1} + w_t$	(state or transition equation)
$z_t = \mathbf{H} y_t + v_t$	(measurement equation)

 w_t , v_t : error terms, with zero mean and variance **Q** and **R**, respectively.

• Based on time t-1 information, the KF generates predictions for y_i: $\begin{aligned} \mathbf{y}_{t|t-1} &= \mathbf{A} \; \mathbf{y}_{t-1|t-1} + \mathbf{B} \; \mathbf{u}_{t} \\ \mathbf{P}_{t|t-1} &= \mathbf{A} \; \mathbf{P}_{t-1} \; \mathbf{A}^{\mathrm{T}} + \mathbf{Q} \end{aligned}$ (conditional variance of y_t) • It also generates an update, once the information t is known: $\mathbf{y}_{t|t} = \mathbf{y}_{t|t-1} + \mathbf{P}_{t|t-1} \mathbf{H}^{T} (\mathbf{F}_{t|t-1})^{-1} \mathbf{e}_{t|t-1}$ $\mathbf{P}_{t|t} = \mathbf{P}_{t|t-1} - \mathbf{P}_{t|t-1} \mathbf{H}^{T} (\mathbf{F}_{t|t-1})^{-1} \mathbf{H} \mathbf{P}_{t|t-1}$

Conditional distributions: KF Application

• We define the forecast error for the observed z_t and its variance as:

$$\begin{aligned} \mathbf{e}_{t|t-1} &= \mathbf{z}_t - \mathbf{z}_{t|t-1} = \mathbf{z}_t - \mathbf{H} \mathbf{y}_{t|t-1} \\ \mathbf{F}_{t|t-1} &= \mathbf{H} \mathbf{P}_{t|t-1} \mathbf{H}^{\mathrm{T}} + \mathbf{R} \end{aligned}$$

Then, we write the joint of distribution of $(y_t, e_t) | I_t$:

$$\begin{pmatrix} y_t \mid I_{t-1} \\ e_t \mid I_{t-1} \end{pmatrix} \sim N \begin{pmatrix} y_{t|t-1} \\ 0 \end{pmatrix}, \begin{bmatrix} P_{t|t-1} & P_{t|t-1}H' \\ HP_{t|t-1} & F_{t|t-1} \end{bmatrix}$$

• Recall a property of the multivariate normal distribution:

$$\mu_{1|2} = \mu_1 + \Sigma_{12} \Sigma_{22}^{-1} (x_2 - \mu_2)$$

$$\Sigma_{1|2} = \Sigma_{11} - \Sigma_{12} \Sigma_{22}^{-1} \Sigma_{21}$$

Then, from the joint, we can easily derive the KF update:

$$\begin{aligned} \mathbf{y}_{t|t} &= \mathbf{y}_{t|t-1} + \mathbf{P}_{t|t-1} \mathbf{H}^{\mathrm{T}} (\mathbf{F}_{t|t-1})^{-1} \mathbf{e}_{t|t-1} \\ \mathbf{P}_{t|t} &= \mathbf{P}_{t|t-1} - \mathbf{P}_{t|t-1} \mathbf{H}^{\mathrm{T}} (\mathbf{F}_{t|t-1})^{-1} \mathbf{H} \mathbf{P}_{t|t-1} \end{aligned}$$

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